

## FDA -222

The FDA-222 motion simulator is designed to be an economic rate table. This model allows testing of several medium and large Inetial Measurement Units (IMU's) or Micro Electro Mechanical Systems (MEMS) sensors simultaneously and also for the development, testing and calibration of stabilized optical sights or startrackers.

This model has two degrees-of-freedom; Roll and Pitch or inner and outer respectively. The outer gimbal has a "U-shape" design allowing unobstructed optical access to the tabletop. The simulator's axes are equipped with stow locks to facilitate the safe loading/unloading of the UUT. The simulator is secured to the facility floor using four leveling wedges.

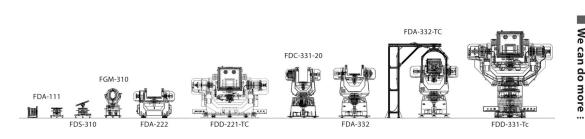


A temperature chamber with gas cooling and electric heating is fastened to the middle axis gimbal as an option.

Slip ring assemblies featuring power rings and shielded signal rings permit electrical access to the UUT and allow to simulate continuous rotation. Beside the standard slip ring configuration, a wide variety of slip ring capsule designs and wiring schematics are available.

AC direct drive brushless motors are used for all the simulator's axes. The servo feedback transducers are also direct mounted to the axes and perform high precise positioning performances.

The ACCUDYNA nonlinear multi-variable controller is embedded in a special console, which has a power cabinet with amplifiers, power supplies, chokes, and motor filters. The controller can be configured as determined by the customer's application. It is capable of providing position, rate and acceleration control either manually from the GUI or remotely through the RS232/RS422 computer interfaces. UDP (Up to 4 kHz) can be an option.





## **FDA-222 PARAMETERS**

UUT SPECIFICATIONS				12Hole-MMC( Ø 6 H7) 50 mm grid-36x
UUT weight UUT dimensions Flatness Material Table top mounting pattern Table top distance from floor Axes intersection distance from floor Electrical lines to UUT		25 Kg (Option: Up to 5 H: 400 mm, D:300 mr 0.03 mm Aluminum (Hard Anoc 50 mm grid M6,12Hol 745 mm 765 mm 50 lines rated 2A,10 li	m dized) dized) de-MMC(ø6H7)	50 50 25 0 0 420 0 420
		(Option: Up to 70 lines) With D-Sub or KPT style type connectors		330
		INNER AXIS (ROLL)		OUTER AXIS (PITCH)
Degrees of freedom				
Angular freedom		Continuous Dire	ct / AC brushles	Continuous (Option: ±180°) ss motors
Position				
Accuracy Repeatability Cmd. resolution	arcsec arcsec deg	< ± 5 P-P < ± 1.5 0.0001		< ± 5 P-P < ± 1.5 0.0001
Rate				
Range Resolution	°/s °/s	± 1000 0.0001		± 1000 (± 100 with limited rotation) 0.0001
Stability (Over 360° interval)	%	< 0.0001 (1 ppm)		< 0.0001 (1 ppm)
Dynamic				
Maximum torque Momentum inertia Bandwidth (-3db, no load) Acceleration (no load)	N.m kg.m² Hz °/s²	36 0.25 Up to 90 ± 8000		180 5.6 Up to 50 ± 1800
Orientation error				
Wobble Orthogonality	arcsec arcsec	< ± 5 P-P	< 5	< ± 5 P-P
Temperature chamber (Option)				
Temperature range Stability Thermal gradiant (Heating & cooling)	°C °C °c/min		-45 to +90 ± 1 ± 3	
Operating and physical cond	itions			
Operating temperature Storage temperature EMC/EMI considerations Rate table dimensions Rate table weight Power supply	°C °C mm kg	(L x W	22 ± 2 0 to 50 cording to IEC6 7 x H) 1270 x 64 770 %, 50 Hz, 3 Pha	
Software				

The specifications identified in this data sheet are representative of standard systems. To satisfy customer specific requirements ACCUDYNA is able to design systems with specifications that are increased or decreased relative to standard systems.

Russian or English

Language of software